A Randomized Construction of Polar Subcodes

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Abstract—A method for construction of polar subcodes is presented, which aims on minimization of the number of low-weight codewords in the obtained codes, as well as on improved performance under list or sequential decoding. Simulation results are provided, which show that the obtained codes outperform LDPC and turbo codes.

I. INTRODUCTION

Polar codes are a novel class of error-correcting codes, which asymptotically achieve the symmetric capacity of memoryless channels, have low complexity construction, encoding and decoding algorithms [1]. However, the performance of polar codes of practical length is quite poor. The reasons for this are their low minimum distance and the suboptimality of the successive cancellation (SC) decoding algorithm.

It was shown that polar codes with CRC under list decoding [2] can provide the performance comparable to that of LDPC codes. Polar subcodes of extended BCH codes were shown to have higher minimum distance than classical polar codes and provide even better performance [3]. Similar performance to have higher minimum distance than classical polar codes. Polar subcodes of extended BCH codes were shown in [6], [7]. Classical polar codes are obtained by taking $F$ to be the set of $n-k$ indices $i$ of bit subchannels $W_i$ with low capacity or high error probability.

B. Polar subcodes

It was suggested in [3] to set frozen symbols not to zero, but to some linear combinations of other symbols, i.e.

$$u_i = \sum_{j<i} V_{s,j} u_j, \: \forall i \in F,$$

where $V$ is a $(n-k) \times n$ constraint matrix, such that distinct rows end in distinct columns $i \in F$, and $s_i$ is the index of the row ending in column $i$. Symbols $u_i$ with at least one term in the r.h.s. of (1) are referred to as dynamic frozen (DFS), and those with $V_{s,j} = 0, j < s_i$, are denoted static frozen. Matrix $V$ can be constructed so that codewords $c_0^{n-1}$ belong to some $(n, k', k, d)$ parent code (e.g. extended BCH) with sufficiently high minimum distance $d$, and the SC decoding error probability $P(F)$ is minimized. The obtained codes are referred to as polar subcodes.

The successive cancellation (SC) decoding algorithm for polar subcodes makes decisions

$$\hat{u}_i = \begin{cases} \text{arg} \max_{u_i \in F_2} W_i(y_i^{n-1}, \hat{u}_i^{t-1}|u_i), & i \notin F \\ \sum_{j<i} V_{s,j} \hat{u}_j, & i \in F. \end{cases}$$

C. List decoding

The original SC decoding algorithm does not provide maximum likelihood (ML) decoding of polar codes. The Tal-Vardy list decoding algorithm [2] was shown to provide substantially better performance. In this section we review the min-sum version of this algorithm [8].

Let $y_i^{n-1}$ be the channel output vector. The decoder keeps $L$ partial information vectors $\hat{u}_0^{n-1}$ together with their scores $R(\hat{u}_0^{n-1}, y_0^{n-1})$. At phase $i$, $0 \leq i < n$, the decoder constructs at most $2L$ possible continuations $\hat{u}_0^{n-1}$ of these vectors, and

$$R(\hat{u}_0^{n-1}, y_0^{n-1}).$$

Given some binary vector $a_0^{n-1}$, we say that it ends in position $j$ iff $a_j = 1$ and $a_l = 0, j < t < n$. It is possible to show that matrix $A_m$ together with a memoryless output symmetric channel $W(y|x)$ gives rise to synthetic bit subchannels with transition probability functions

$$W_m(i, y_i^{n-1}, \hat{u}_i^{t-1}|u_i) = \frac{1}{2^{n-1}} \prod_{j=0}^{n-1} W(y_j|(u_0^{n-1} A_m)_j).$$

One can compute the capacity $C_{m,i}$ and bit error rate $P_{m,i}$ in each of the subchannels $W_m(i)$ using the techniques presented in [6], [7]. Classical polar codes are obtained by taking $F$ to be the set of $n-k$ indices $i$ of bit subchannels $W_i$ with low capacity or high error probability.
computes their scores. Then \(L \) vectors \( \hat{u}_0^0 \) with the highest scores are selected, and the remaining ones are killed. At phase \( n \) the algorithm returns vector \( \hat{u}_0^{0,n-1} \) with the highest score.

The score of vector \( \hat{u}_0^0 \) is given by
\[
R(\hat{u}_0^0, y_0^{n-1}) = R(\hat{u}_0^{i-1}, y_0^{n-1}) + \tau(\hat{u}_i, S_m^{(i)}(\hat{u}_0^{i-1}, y_0^{n-1})),
\]
where
\[
\tau(u, S) = \begin{cases} 0, & \text{if } (-1)^n = \text{sgn } S \\ -|S|, & \text{otherwise} \end{cases}
\]
is the penalty function, and \( S_m^{(i)}(\hat{u}_0^{i-1}, y_0^{n-1}) \) are the approximate log-likelihood ratios, which are given by
\[
S_{\lambda}^{(2i)}(\hat{u}_0^{2i-1}, y_0^{N-1}) = \text{sgn}(a) \text{sgn}(b) \min(|a|, |b|),
\]
\[
S_{\lambda}^{(2i+1)}(\hat{u}_0^{2i+1}, y_0^{N-1}) = (-1)^{2i}a + b,
\]
where \( a = S_{\lambda}^{(i)}(\hat{u}_0^{2i-1} \oplus \hat{u}_0^{2i-1}, y_0^{N-1}) \), \( b = S_{\lambda}^{(i)}(\hat{u}_0^{2i-1}, y_0^{N-1}) \), and \( S_0^{(i)}(y) = \log \frac{W(y)}{W(\hat{y})} \).

The complexity of this algorithm can be substantially reduced by employing sequential decoding techniques [4].

The error probability of the Tal-Vardy algorithm is given by
\[
P(L) = P_{ML} + P(E(L)|C),
\]
where \( P_{ML} \) is the maximum likelihood decoding error probability, \( C \) is the event corresponding to the maximum likelihood decoder producing the correct codeword \( \hat{u}_0^{0,n-1}A_m \), and \( E(L) \) is the event corresponding to the score \( R(\hat{u}_0^0, y_0^{n-1}) \) of the correct vector becoming lower than the scores of \( L \) incorrect vectors \( \hat{u}_0^0 \) at some intermediate phase, so that the correct vector is killed by the decoder. The value of \( P_{ML} \) can be estimated using the weight distribution of the code. At high SNR \( P_{ML} \) primarily depends on the minimum distance \( d \) and error coefficient of the code, i.e. the number \( w_d \) of codewords of weight \( d \). To the best of our knowledge, there are still no techniques for computing \( P(E(L)|C) \). However, experiments show that this quantity increases with \( P_{SC} \), the successive cancellation decoding error probability of the code.

### III. A RANDOMIZED CODE CONSTRUCTION

Polar subcodes of extended BCH codes were shown to provide substantially better performance compared to classical polar codes under list and sequential SC decoding [3]. It turns out that list/sequential decoding with very large list size \( L \) is needed in order to implement near-ML decoding of polar subcodes with even modestly high minimum distance \( d \). For small \( L \) almost all error events are caused by the decoder killing the correct vector \( \hat{u}_0^0 \) at early phases. Therefore, we propose a code construction, which is targeted to be efficiently decodable by list/sequential algorithms with small \( L \).

#### A. Eliminating low-weight codewords from a polar code

In order to obtain a \((n, k)\) polar code \( C \), we propose to construct a \((n, k+\ell)\) classical Arikan polar code \( C' \), called base code, and then select a random \( k\)-dimension linear subspace of this code. Let \( d' \) be the minimum distance of \( C' \), and let \( w_1 \) be its weight distribution. It is possible to show [9] that the expected number of codewords of weight \( s \in C \) is given by
\[
E[w_a] = w_1^a \frac{2^k - 1}{2^{k+1} - 1} \approx w_1^a 2^{-t}, s > 0,
\]
provided that all linear subspaces are selected equiprobably.

The parameter \( t \) should be selected so that the expected number \( E[w_d'] \) of codewords of weight \( d' \) in code \( C \) becomes sufficiently small. If \( E[w_d'] < 1 \), then with high probability the minimum distance \( d \) of \( C \) is higher than \( d' \).

It was shown in [10] that the error coefficient of a classical polar code \( C' \) of length \( n = 2^m \) with the set of frozen symbols \( F' \), i.e. the number of codewords of weight \( d' \), is given by
\[
w_1^{d'} = 2^{m-r} \sum_{g \in [n]\backslash F'} 2^{\lambda_g},
\]
where \( r = \min_{v \in [g]} \text{wt}(v) \), \( \lambda_g \) is the list of indices of zero bits in integer \( g \), and \( |(i_0, \ldots, i_{m-r-1})| = \sum_{j=0}^{m-r-1} (i_j - j) \). It can be also seen that any codeword of \( C' \) of weight \( d' = 2^m \) is obtained as a linear combination of a weight-1 row of matrix \( A_m \), and possibly some other rows of this matrix.

Taking a random linear subcode of \( C' \) is equivalent to selecting codewords of \( c = uA_m \in C \), which satisfy \( cH^T = 0 \), where \( H \) is a \( t \times n \) matrix randomly selected from the set of full-rank binary matrices. Alternatively, one can randomly select a full-rank \( t \times n \) matrix \( V = H A_m \), so that the constraint matrix of code \( C \) is given by \( V = \left( V' \right) \), where \( V' \) is the constraint matrix of code \( C' \) consisting of weight-1 rows. It can be assumed without loss of generality that the positions of last non-zero elements in the rows of \( V' \) are distinct.

In order to simplify the implementation, as well as to obtain codes better decodable by the Tal-Vardy list decoding algorithm, we propose to impose dynamic freezing constraints (1) onto symbols \( u_i \), such that \( i \) are the smallest possible values, and all non-frozen symbols \( u_i : \text{wt}(i) = r \), participate in (1) with high probability. Since any weight-2\(^r\) codeword \( c_0^{n-1} = u_0^{n-1} A_m \) corresponds to \( u_0^{n-1} \) having \( u_i = 1 \) for some \( i : \text{wt}(i) = r \), the latter requirement ensures that most of the low-weight codewords are eliminated from \( C' \).

The former requirement enables the list decoder to process the corresponding constraints at the earliest possible phases, reducing thus the probability of the correct vector being killed. Employing this approach, however, causes (6) to be an imprecise estimate of the weight distribution components of the obtained code.

The constraints obtained with this approach are referred to as type-A dynamic freezing constraints (DFC-A), and the corresponding symbols in l.h.s of (1) are called type-A DFS.

#### B. Design of codes with better list decodability

Let \( u_0^{n-1} \) be the vector corresponding to the transmitted codeword. Consider the case of \( \tau(u_j, S_m^{(j)}(\hat{u}_0^{i-1}, y_0^{n-1})) < 0 \) for some \( j \notin F' \), i.e. an error event of the SC algorithm. Such
event causes the Tal-Vardy list decoder to consider an incorrect vector $\hat{u}_0$ with $R(\hat{u}_0, y_0^{n-1}) > R(u_0, y_0^{n-1})$.

It was observed in [11] that classical polar codes exhibit very low bit error rate. Indeed, most of erroneous received symbols correspond to low-magnitude log-likelihood ratios. Hence, with sufficiently high probability the sign of the LLRs $S_1^i(\hat{u}_0^{i-1}, y_0^{n-1}), i > j$, obtained from (5) may be correct (i.e., agree with the value of $u_i$) even if $\hat{u}_i \neq u_j$ for some $j < i$. Hence, the decoder may need to process many frozen symbols before the score of an incorrect path $\hat{u}_0$ is sufficiently penalized according to (3). It may happen that the score $R(\hat{u}_0, y_0^{n-1})$ becomes lower than the scores of $L$ incorrect paths, so that the Tal-Vardy list decoder kills $u_0$, i.e., makes an error.

In order to reduce probability of such events we propose to select $q$ symbols at corresponding to most reliable bit subchannels, which would be static frozen in the classical polar code construction method, and impose on them dynamic freezing constraints with random coefficients. Such constraints are referred to as type-B dynamic freezing constraints (DFC-B), and the corresponding $u_0$ are denoted type-B dynamic frozen symbols (DFS-B).

Let $u_i$ be a DFS-B. For an incorrect path $\hat{u}_0$, with high probability one obtains $u_i \neq \sum_{j<i} V_{s,i,j} u_j$, so that the r.h.s. values of this expression does not agree with the sign of $S_1^i(\hat{u}_0^{i-1}, y_0^{n-1})$. This causes the scores $R(\hat{u}_0^{i-1}, y_0^{n-1})$ of most incorrect paths $\hat{u}_0$ to quickly decrease with $i$.

C. Shortening

The classical construction of polar codes is limited to length $2^n$. However, practical systems require codes of other lengths $n$. Shortening can be used to obtain codes of arbitrary length. For the sake of simplicity, we do not consider optimization of a shortening pattern, and use the method suggested in [12]. Namely, we set $u_i = 0, n \leq i < 2^n$ (shortening constraints), and eliminate from the vector $u_0^{n-1} A_m$ symbols with indices $r_m(i)$, where

$$r_m \left( \sum_{j=0}^{m-1} i_j 2^j \right) = \sum_{j=0}^{m-1} i'_{m-1-j} 2^j$$

is the bit reversal function. By examining the matrix $A_m$, one can see that these symbols are equal to zero. Observe that shortening should be taken into account while evaluating the reliability of bit subchannels $W_{m}(i)$.

D. The proposed code construction algorithm

Below we present a summary of the proposed method for construction of an $(n, k)$ randomized polar subcode. Here $t$ and $q$ denote the number of type-A and type-B dynamic freezing constraints, respectively.

1) Let $V$ be a $(2^m - k) \times 2^m$ matrix initially filled with 0.
2) [Shortening constraints] Let $s = 2^m - n$. Set $V_{0, s-1, \ldots, 2n-1}$ to a $s \times s$ identity matrix.
3) Let $F \subset [n]$ be the set of $n - k - t$ indices of least reliable bit subchannels $W_m(j), 0 \leq j < n$, induced by $A_m$. Let $N = [n] \backslash F$. Let $\tilde{F}$ be the set of $q$ elements of $F$ corresponding to the most reliable subchannels, and let $\tilde{F} = F \backslash \tilde{F}$.
4) Let $w = \min_{i \in N} wt(i)$ be the minimal weight of indices of type-A dynamic frozen symbols.
5) Let $Z = \{z_0, \ldots, z_{t-1}\} \subset N$, be the set of $t$ integers, which is constructed by selecting from $N$ maximal integers of weight $w, w + 1, \ldots$, until $t$ integers are selected.
6) [DFC-A] For $j$ from 0 to $t - 1$ do:
   a) Set $V_{s,j} := 1$.
   b) Set $V_{s,i}, i \in N, i < z_j$ to independent random equiprobable binary values (IREPBV).
   c) Let $s := s + 1$.
7) [Static freezing constraints] For $i$ from 0 to $n - k - q - t - 1$ do:
   a) Set $V_{s,i} := 1$, where $f_i$ is the $i$-th element of $\tilde{F}$.
   b) Set $s := s + 1$.
8) [DFC-B] For $i$ from 0 to $q - 1$ do:
   a) Let $V_{s,i} := 1$, where $f_i$ is the $i$-th element of $\tilde{F}$.
   b) Set $V_{s,i}, j \in N, j < f_i$ to IREPBV.
   c) Let $s := s + 1$.

In practice, the elements of $V_{s,j}$ at steps 6.b and 8.b in the above algorithm can be obtained from a pseudo-random number generator (PRNG). Hence, the code can be completely specified by the seed value of the PRNG, parameters of the channel $W(y|x)$, and numbers $n, k, t, q$. It can be seen that the complexity of this algorithm is $O(k(t+q))$ calls to the PRNG. Recall, that construction of a constraint matrix of a polar subcode of an $(n, k, d)$ extended BCH code with $(n-k)\times$ check matrix $H$ requires Gaussian elimination to be performed on matrix $HA^T_{m}$, which requires $(n-k)n^2$ operations [3].

Due to lack of analytic methods for performance evaluation of polar codes under list/sequential decoding, we are not able to give optimal values of $t$ and $q$. However, experiments suggest that setting $t = \min(m, n-k), m = \lfloor \log_2 n \rfloor$ and

$$q = \max(0, \min(Q - t, n - k - t)),$$

where $Q = 64$, results in codes with good performance under list decoding with $L = 32$. In some cases better codes can be obtained by careful selection of these parameters.

IV. NUMERICAL RESULTS

Table I illustrates the error coefficient of $(n = 1024, k = 512)$ randomized polar subcodes constructed for AWGN chan-
nel with BPSK modulation and $E_b/N_0 = 1.5$ dB. For each $t$ and each $q$ 50 codes were constructed, and their low-weight codewords were obtained using the algorithm given in [13]. In all cases the minimum distance of the constructed codes was at least 16. We report the error coefficient $w_{16}$ of the corresponding $(n, k+t)$ base code given by (7), the successive cancellation decoding error probability $P_{SC}$, and the minimal, maximal and average values of $w_{16}$ for the constructed codes, denoted $\min w_{16}, \max w_{16}, \overline{w}_{16}$, respectively. It can be seen that for small $t$ and $q = 0$ the value of $\overline{w}_{16}$ is quite close to that predicted by (6). However, for $t > 7$ and $q = 0$ the average error coefficient of the constructed codes is considerably higher than $E[w_{16}]$ for a uniformly selected subcode of the base code. The reason for this is that the above presented code construction algorithm does not implement equiprobable selection of $k$-dimensional linear subspaces from the $(k+t)$-dimensional classical polar code $C'$. It can be seen that the codes obtained with $q > 0$ (which are not subcodes of $C'$) have substantially lower $\overline{w}_{16}$.

In both cases the average error coefficient $\overline{w}_{16}$ quickly decreases with $t$. However, increasing $t$ requires one to unfreeze some symbols corresponding to unreliable bit subchannels, so $P_{SC}$ and $P(E(L)|C)$ increase with $t$, and at some point the performance becomes dominated by the suboptimality of the list/sequential decoding algorithm. Figure 1 illustrates the performance of the considered codes in the case of AWGN channel with BPSK modulation and sequential decoding [4]. For each combination of $t, q$ a code was selected with $w_{16} \approx \overline{w}_{16}$. For comparison, we report also the performance of the (1024, 512, 24) polar subcode of an extended BCH code (PBCH) and a polar code with CRC [3]. It can be seen that the codes with $q > 0$ outperform the corresponding codes with $q = 0$, and the best performance in the low-SNR region is provided by the code with $t = 11, q = 53$. For $E_b/N_0 > 2$ dB the best performance is obtained in the case of $t = 16, q = 48$ due to much lower error coefficient of the corresponding code. For $E_b/N_0 \leq 2.1$ dB the randomized polar subcode with $t = 11, q = 53$ provides up to 0.1 dB gain with respect to the PBCH code and 0.2 dB gain compared to the polar code with CRC-16. Observe, that the code obtained with $t = 16, q = 0$ also outperforms the polar code with CRC. The latter code can be considered as an instance of the proposed construction with $q = 0$ and $Z = \{n-c, \ldots, n-1\}$, where $c = 16$ is the number of bits in CRC. The reason for this gain is that the proposed approach enables the decoder to process the dynamic freezing constraints at earlier phases, reducing thus the probability of the correct vector being killed.

Figures 2 and 3 illustrate the performance of polar subcodes of dimension $k = 1024$ and $k = 4096$. We report the results for the case of the proposed randomized polar subcodes (RP), polar subcodes of eBCH codes (PBCH), and a polar code with CRC-16. For comparison, we provide also the results for AR4JA LDPC codes [5] under shuffled BP decoding [15] and an LTE turbo code. It can be seen that for $k = 1024$ and $L = 32$ the proposed randomized polar subcodes outperform the polar code with CRC, and provide...
performance comparable to that of LDPC codes. For \( L = 512 \)
the proposed codes provide up to 0.5 dB gain with respect to
LDPC, turbo and polar-CRC codes. In the case of \( k = 4096 \)
list size \( L \) needs to be increased in order to obtain gain
with respect to the LDPC codes. The reason is that although
the fraction of mediocre (i.e. those having Bhattacharyya
parameters \( 0 < a < Z_{\text{th}}^i < b < 1 \) for some fixed \( a, b \)) bit
subchannels decreases with \( m \), the absolute number of such
subchannels corresponding to unfrozen symbols, which with
high probability cause \( E(L) \) events, increases with \( m \) [14].
Observe that the (2048, 1024) polar code with CRC exhibits
noticeable performance loss in the case of sequential decoding.
However, the performance of the proposed randomized polar
subcodes is essentially the same in the case of both decoding
algorithms.

Figure 4 illustrates the average number of operations per-
formed by the decoders of the considered codes. For polar
and turbo codes, decoding involves only summations and com-
parisons, while for LDPC codes the algorithm in [15] makes
use of summations and \( \log(\tanh(\cdot)) \) function. It can be seen
that the (2048, 1024) randomized polar subcode provides not
only better performance, but also lower decoding complexity
compared to the polar code with CRC. A surprising result is
that randomized polar subcodes outperform polar subcodes of
\( \text{eBCH} \) codes with much higher minimum distance even in the
high-SNR region.

Figure 5 illustrates the SNR needed for achieving codeword
error rate \( 10^{-3} \) in the case of BPSK modulation for different
values of code rate \( R = k/n \) and dimension \( k \) for the case of
\( q = 0 \) and \( q \) given by (8). It can be seen that employing DFS-B
provides up to 0.3 dB gain, especially for low-rate codes.

V. CONCLUSIONS

In this paper a randomized construction of polar subcodes
was proposed. The construction relies on two types of dynamic
freezing constraints, which allow one to reduce the number of
low-weight codewords in the obtained code and decrease the
probability of a correct path being killed by the Tal-Vardy list
decoder. The obtained codes were shown to outperform LDPC
and turbo codes, and have lower complexity in the case of
sequential decoding compared to polar codes with CRC.

The proposed construction is a heuristical one. It relies on
some observations on the behaviour of the Tal-Vardy list
decoding algorithm. Any progress in its analytic performance
evaluation may result in an improved code design.

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Fig. 4. Decoding complexity of codes with \( k = 1024 \)
Fig. 5. The gain of type-B dynamic frozen symbols